



RFID
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Use of Drones for Outdoor Inventory

The cases of Metal Pipes and Cattle

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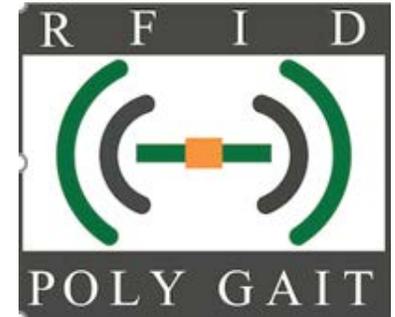
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& Students: Neil Wolfe, Allen Duong, Maxime Jeanneau, Tori Carson



Use of UAV-RFID for Oilfield Tubulars

Hundreds or thousands tubulars



Across large fields

Labor Intensive Inventory



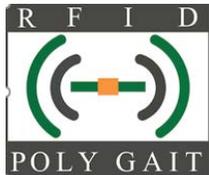
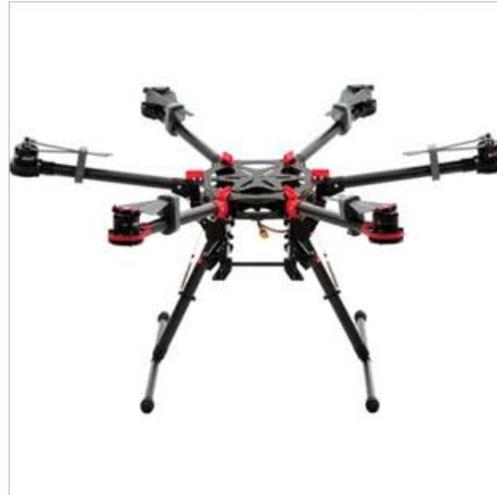
RFID to the Rescue

Passive UHF RFID

Tag cost = \$0.15

Adhered to pipe cap
or to foam insulator

RFID reader on UAV



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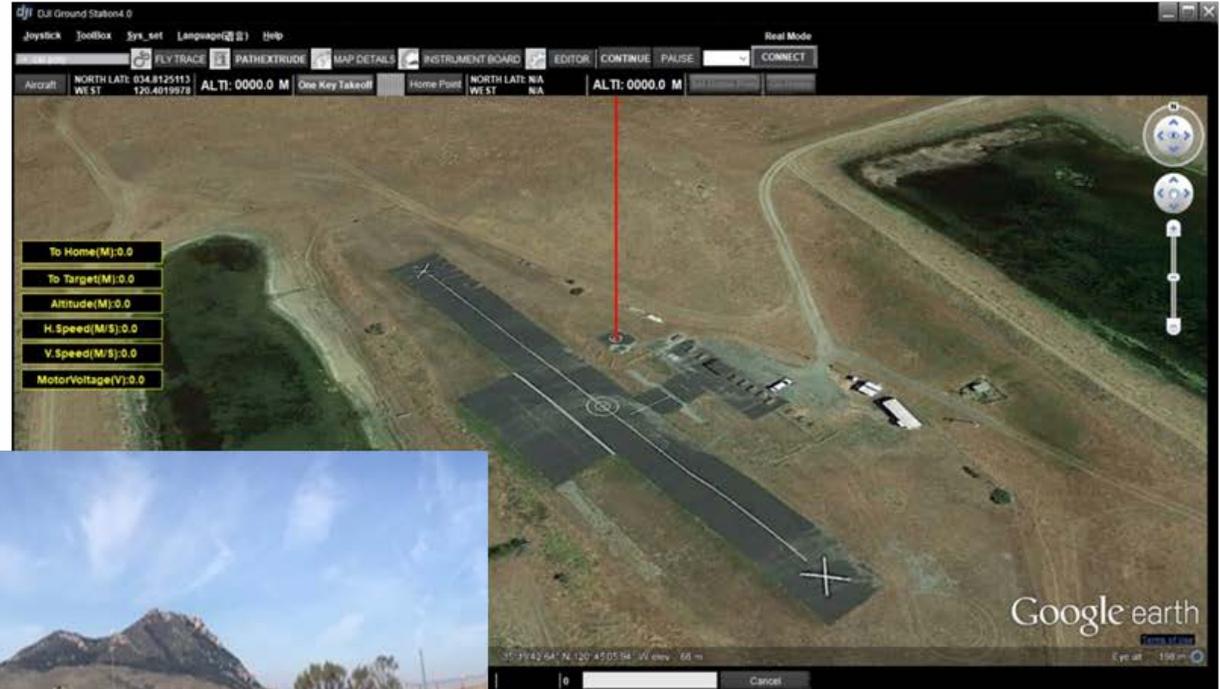
Experiment #1 – Establish Base Read Range

Experimental Flight Range

Read range testing

Zip ties for tag attachment

Promising results – 12'



Experiment #2 – Reading Reliability on Oilfield Tubulars

Santa Maria Holdings Site

Oil drilling pipes

Tags on insulation strips

Results: 3m 100% read 2
minute hover time



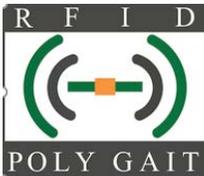
Experiment #3 – Reading 2 Tag Types

Cal Poly Experimental Site

Insulated hot water pipes

Insulated tags on metal
Labels on pipe insulation

Results: 2.5m 95% read
2 minute hover time



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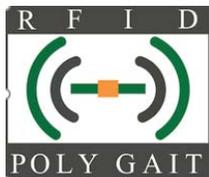
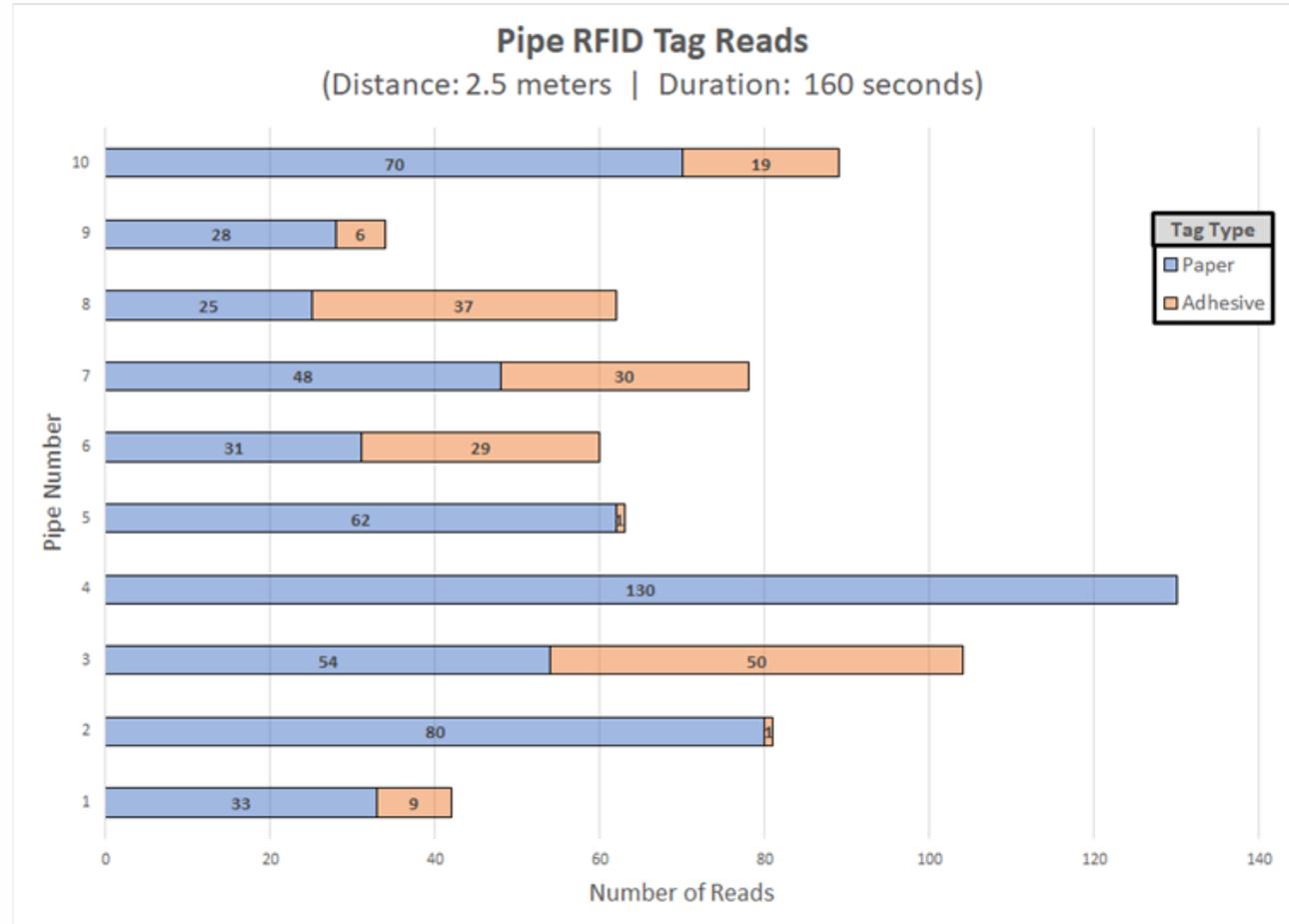
Number of Tag Reads – Reading Reliability

Variability is common

Experiment with tag types

Experiment with insulation

Results: 2.5m 95% read with adhesive,
100% read of paper tags



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Conclusions and Future Research

Variability is common

Experiment with tag types

Experiment with insulation

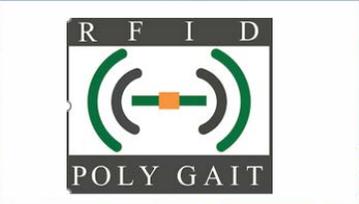
Results: Promising, require more experimentation: layouts, materials, environmental conditions



Use of UAV-RFID for Grazing Cattle Inventory



Livestock Tracking



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UAV-RFID *System Constraints*

RFID scanning radius

350 ft \approx 106m

UAV Flight Speed

16 m/s

Ranch Area

2,562 acres

RFID scanning area

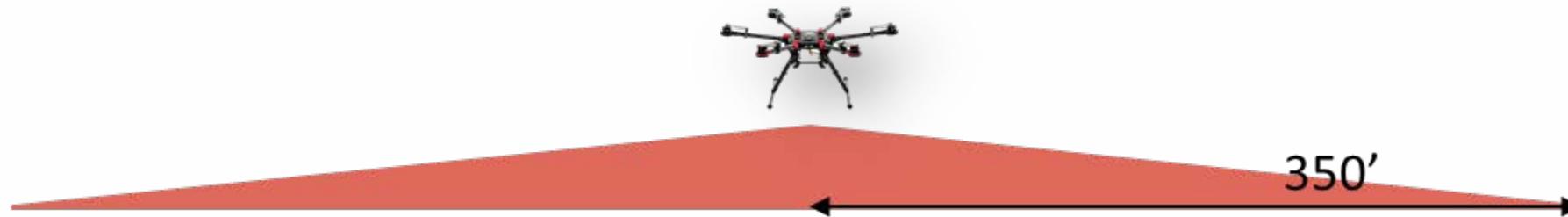
35753 m²

UAV Flight Time per Charge

15 min

Intensive Grazing Pasture Area

up to 293 acres



Problem

To utilize the RFID-UAV system for cattle tracking, the following must be considered:

- *The location of each cow is unknown within the pasture.*
- *The UAV must fly within 350' of each cow.*
- *The UAV flight time is limited to 15 minutes.*

Alternatives Considered

System Adjustments

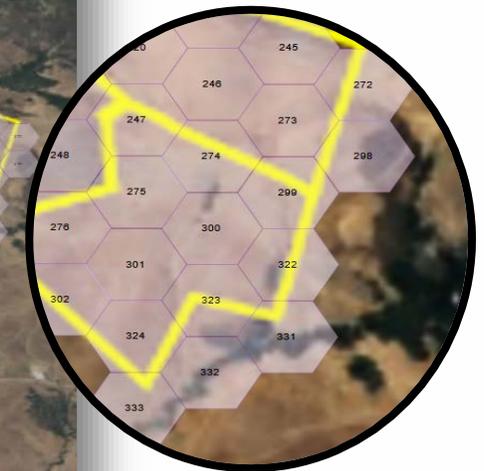
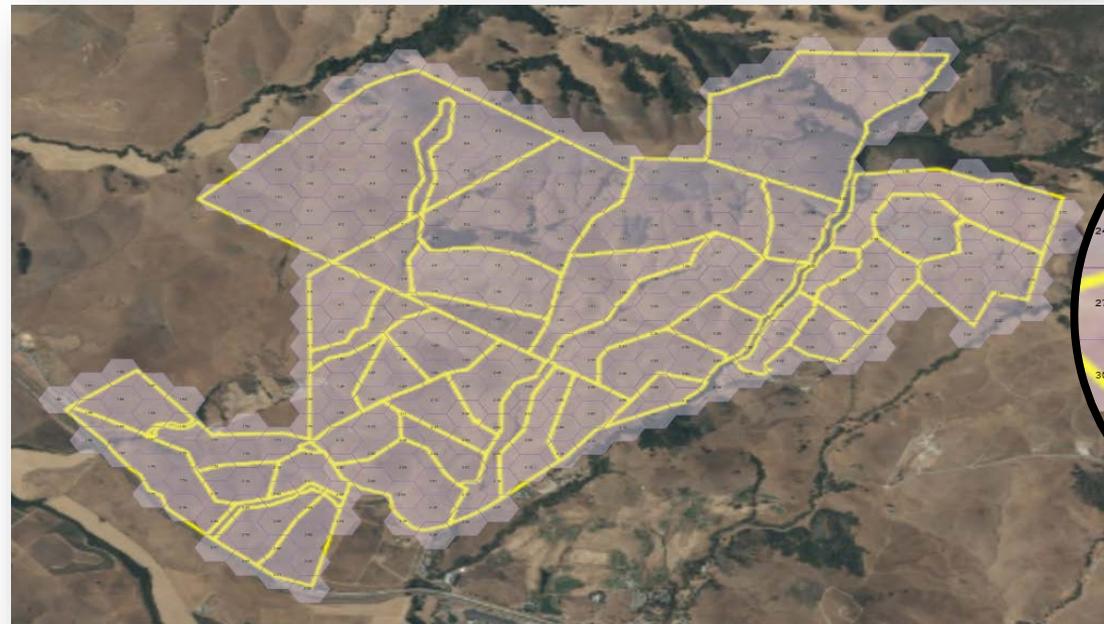
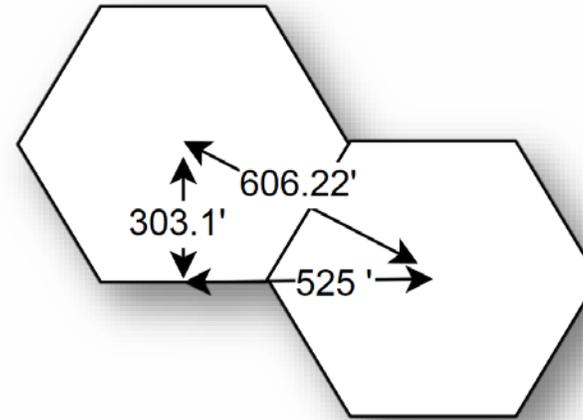
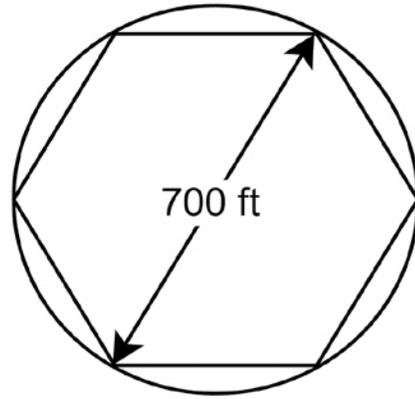
- Increase the flight time
- Enhance read range
- Additional UAV + RFID interrogator
- Reduce the flight path

Path Optimization Method – *Traveling Salesman Problem*

1. Identify Nodes
2. Heuristic Approach to Minimize Number of Nodes
3. Traditional TSP Solution

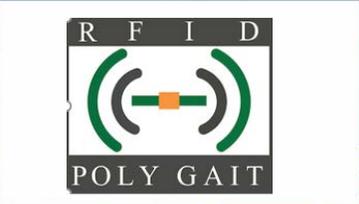
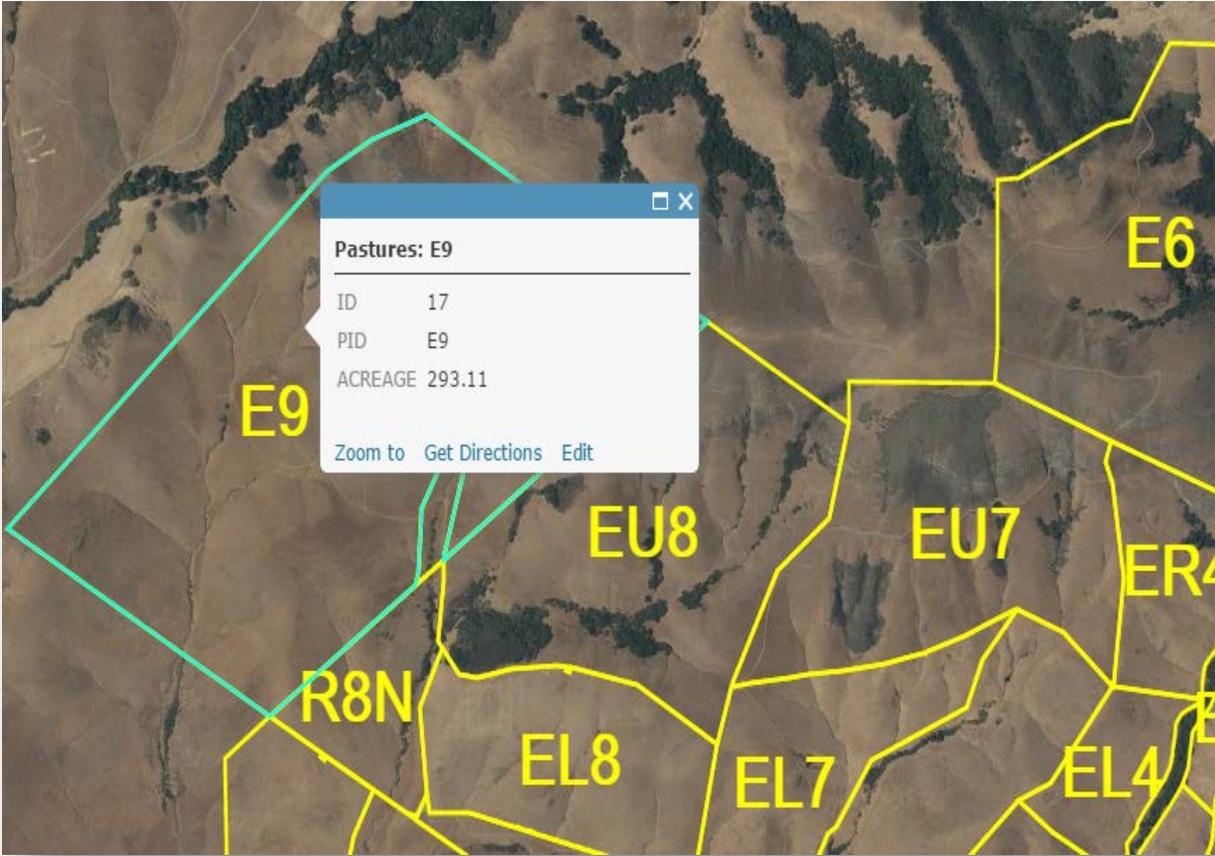
Tiling

- Hexagonal Lattice
- Heuristic approach to minimize nodes



Minimum Number of Nodes Visited

$$293.11 \text{ acres} \times \frac{43,560 \text{ft}^2}{1 \text{ acre}} \times \frac{\text{area scanned per node}}{384,845 \text{ft}^2} \approx 33 \text{ nodes}$$



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Traveling Salesman Problem

Objective Function

Minimize $\sum c_{ij}x_{ij}$

◦ subject to

- $\sum_i x_{ij} = 1 \forall_i$
- $\sum_j x_{ji} = 1 \forall_j$
- $0 \leq x_{ij} \leq 1$ x_{ij} (integer)
- $u_i - u_j + nx_{ij} \leq n - 1, \forall i, j \in N - \{1\}, i \neq j$

Variables

$$x_{ij} = \begin{cases} 1 & \text{if arc } ij \text{ is in the tour} \\ 0 & \text{otherwise} \end{cases}$$

u: sequence in which node i is visited

n: number of nodes in tour

N: total number of nodes

c: arc length

Pasture E9

Path Length

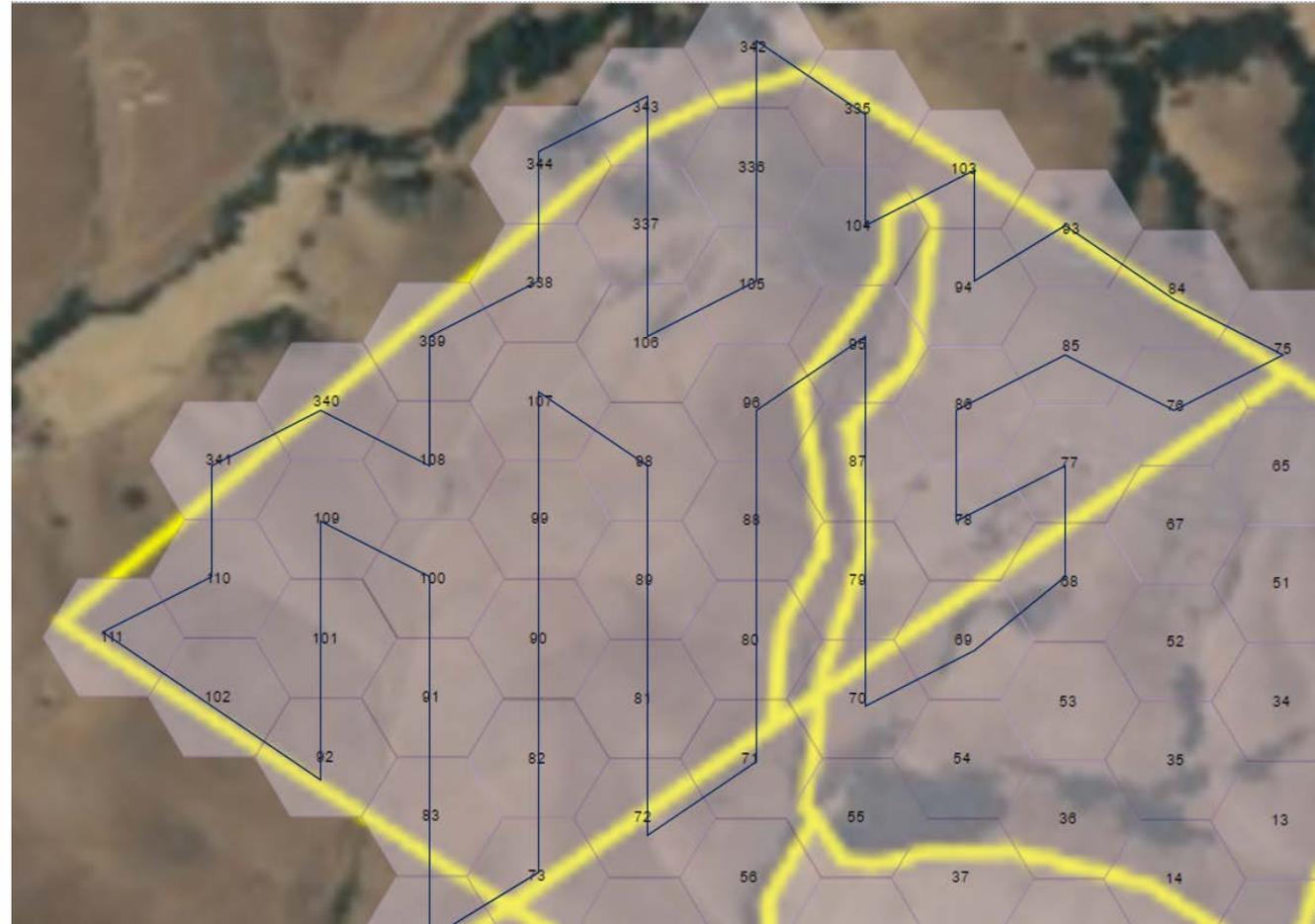
32,129.5ft

Flight Time

32,129.5ft x (52.5ft/s x
60s/min)

+ Ascent /Descent Time

= **10.21 minutes**



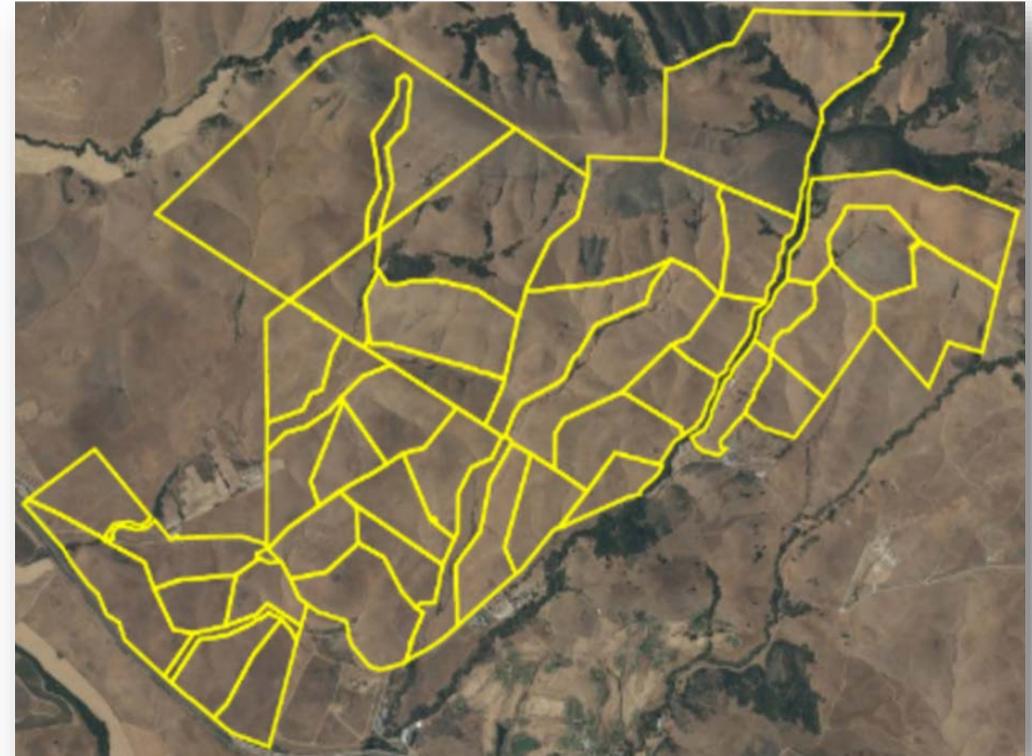
Walters & Escuela Ranches

Minimum Number of Nodes Visited

$$2562 \text{ acres} \times \frac{43,560 \text{ft}^2}{1 \text{ acre}} \times \frac{\text{area scanned per node}}{384,845 \text{ft}^2} \approx 290 \text{ nodes}$$

Time to Travel to all Nodes

$$290 \text{ nodes} \times 700 \text{ft between nodes} \div \frac{52.5 \text{ft}}{\text{s}} = 64.47 \text{ min}$$

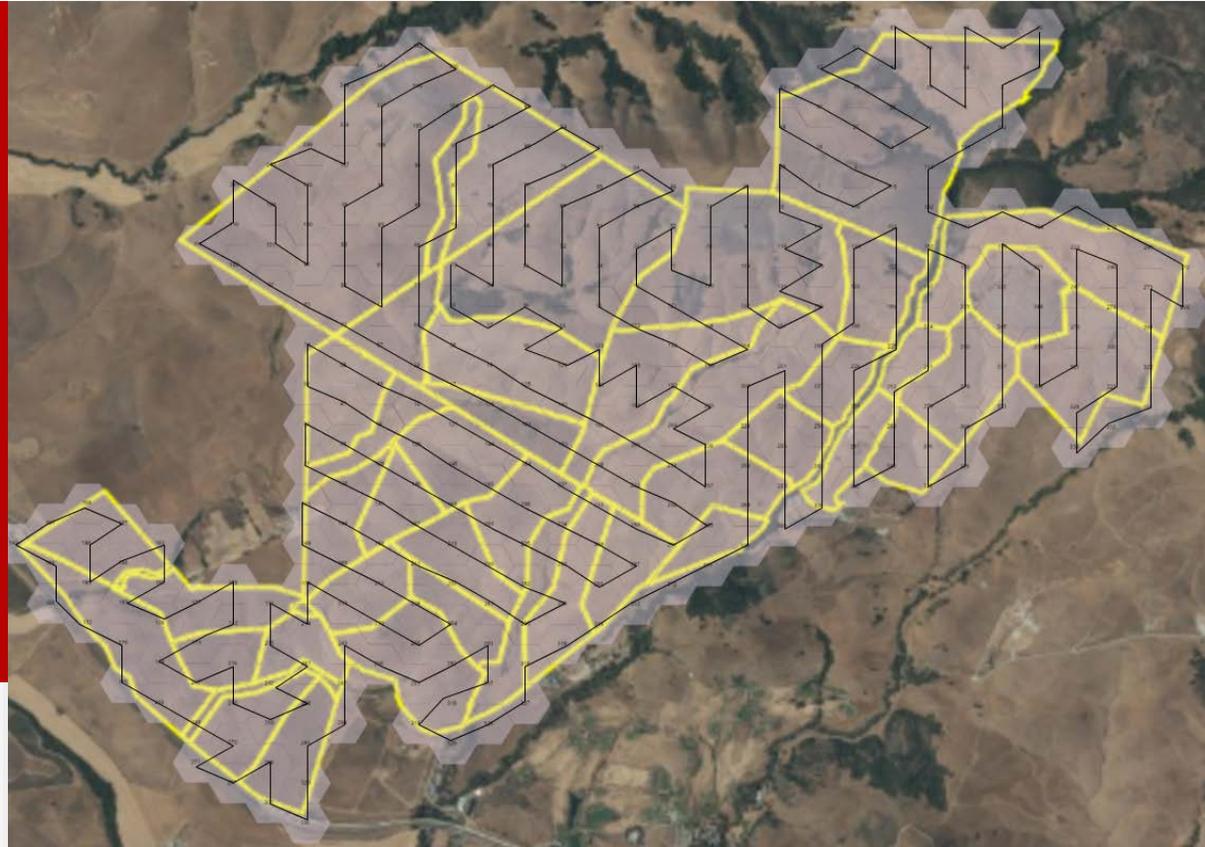


Traditional Grazing

205,508ft

65 min total flight time

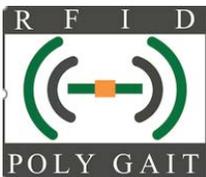
5 Flights



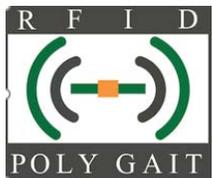
Future @ PolyGAIT

- R&D Goals
 - Leading edge technological innovation and process development, additional industries
 - Hands-on educational methods producing top performing, collaborative, industry leaders
- Collaboration
 - Global & Inclusive
 - Cross-Disciplinary
 - Cross-Profit (Non-Profit w/For Profit)

Thank you!!!



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